

## Basic Theory of linear systems in normal form:

The Normal form of a system of  $n$  linear differential equation can be expressed as

$$X'(t) = A(t)X(t) + F(t), \quad (*)$$

if  $F(t) = 0$ , then we call it homogeneous system, otherwise the system is nonhomogeneous.

The initial value problem for the normal system  $(*)$  is the problem finding a differentiable vector function  $X(t)$  that satisfies the system on an interval  $I$  and also satisfies the initial condition  $X(t_0) = X_0$ , where  $t_0$  is a given point on  $I$  and  $X_0 = \begin{bmatrix} x_{1,0} \\ x_{2,0} \\ \vdots \\ x_{n,0} \end{bmatrix}$  is a given vector.

Now we have some basic results as follows:

### Theorem (Existence and Uniqueness)

If the entries of the matrices  $A(t)$  and  $F(t)$  be continuous on an open interval  $I$  that contains the point  $t_0$ , then for any choice of the initial vector  $X_0$ , there exist a unique solution  $X(t)$  on the whole interval  $I$  to the initial value problem

$$X'(t) = A(t)X(t) + F(t), \quad X(t_0) = X_0$$

### Definition:

↳ Linearly independent & Linearly dependent:

The vector functions  $X_1(t), X_2(t), \dots, X_n(t)$  are linearly dependent on an interval  $I$  if there exists numbers  $c_1, c_2, \dots, c_n$ , not all zero, such that

$$c_1 X_1(t) + c_2 X_2(t) + \dots + c_n X_n(t) = 0, \quad \forall t \in I.$$

If this identity is satisfied only if

$c_1 = c_2 = \dots = c_n = 0$ , the vector functions  $X_1(t), X_2(t), \dots, X_n(t)$  are called linearly independent on  $I$ .

- Any system of  $n$  linearly independent solutions  $x_1(t), x_2(t), \dots, x_n(t)$  is called fundamental system of solutions.

### 27 Wronskian:

The Wronskian of  $n$  vector functions  $x_1(t), x_2(t), \dots, x_n(t)$  is defined to be the real-valued function

$$W(t) = W[x_1, x_2, \dots, x_n](t) = \begin{vmatrix} x_{11}(t) & x_{12}(t) & \dots & x_{1n}(t) \\ x_{21}(t) & x_{22}(t) & \dots & x_{2n}(t) \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1}(t) & x_{n2}(t) & \dots & x_{nn}(t) \end{vmatrix}$$

where  $x_{ij}(t)$  are the coordinates of the vector function  $x_i(t), \dots, x_n(t)$ .

- The set of solution vectors  $x_1(t), \dots, x_n(t)$  is linearly independent on  $I$  if & only if their Wronskian  $W(t)$  is non zero for any  $t$  in the interval.

### • Theorem: (Representation of solutions)

Let  $x_p$  be a particular solution to the nonhomogeneous system  $x'(t) = A(t)x(t) + F(t)$  on the interval  $I$ , & let  $\{x_1, x_2, \dots, x_n\}$  be a fundamental solution set on  $I$  for the corresponding homogeneous system

$$x'(t) = A(t)x(t)$$

Then every solution to the nonhomogeneous system on  $I$  can be expressed in the form

$$x(t) = x_p + c_1 x_1(t) + c_2 x_2(t) + \dots + c_n x_n(t)$$

where  $c_i$ 's are constants.

Ex.  $\rightarrow$  Let the vector functions given by  $x_1(t) = \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{3t}$ ,  $x_2(t) = \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-t}$  are solutions to the system  $x'(t) = A(t)x(t)$ , check whether they form a fundamental solution set. If yes, then find the general solution.



Ans  
Ans:

The Wronskian for the vector function  $X_1(t)$  &  $X_2(t)$

$$W(X_1, X_2) = \begin{vmatrix} 2e^{3t} & e^{-t} \\ e^{3t} & -e^{-t} \end{vmatrix} = -2e^{2t} - e^{2t} \\ = -3e^{2t} \neq 0 \quad \forall t$$

hence the sol<sup>n</sup>s  $\{X_1(t), X_2(t)\}$  are linearly independent which means they form a fundamental sol<sup>n</sup> set.

① The general sol<sup>n</sup> for  $X'(t) = A(t)X(t)$  is given by

$$X(t) = c_1 X_1(t) + c_2 X_2(t) \\ = c_1 e^{3t} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

Ex.

② Consider the linear system

$$X' = \begin{bmatrix} 2 & -1 \\ 3 & -2 \end{bmatrix} X + \begin{bmatrix} e^t \\ t \end{bmatrix}$$

Verify that the vector functions

$X_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t$ ,  $X_2 = \begin{bmatrix} 1 \\ 3 \end{bmatrix} e^{-t}$  are sol<sup>n</sup> to the homogeneous system on  $(-\infty, \infty)$ , and that

$$X_p = \frac{3}{2} \begin{bmatrix} te^t \\ te^t \end{bmatrix} - \frac{1}{4} \begin{bmatrix} e^t \\ 3e^t \end{bmatrix} + \begin{bmatrix} t \\ 2t \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \end{bmatrix} \text{ is a}$$

Particular sol<sup>n</sup> of it. Also find the general sol<sup>n</sup>.

→ Home work!

Exercise:

③ Show that  $x = t+1$ ,  $y = -5t-2$  is a particular sol<sup>n</sup>

of  $\frac{dx}{dt} = 5x + 2y + 5t$

$\frac{dy}{dt} = 3x + 4y + 17t$

and give the general sol<sup>n</sup>.